

PTU-D100-ISM E-SERIES

Midsize, Inertially Stabilized Pan/Tilt Unit

The PTU-D100-ISM E-Series integrates a powerful MEMs gyro to provide active inertially stabilized pointing with real-time control for payloads up to 20 pounds. Stabilization improves images while on the move and allows communications links to be maintained from air, ground, or sea platforms. The PTU-D100-ISM E-Series is an ideal OEM platform for a wide range of applications including slew-to-cue, video tracking, antenna tracking, and more.

The PTU-D100-ISM E Series has been proven in a wide range of missioncritical applications for positioning of cameras, lasers, antennas, or other instruments in both fixed and mobile environments. It is designed for high duty cycles and reliable operation 24/7 in harsh all-weather environments.

The latest evolution of FLIR pan-tilts incorporates a powerful 32-bit core electronics platform and real-time operating system to deliver superior motion control fidelity and improve performance.

KEY FEATURES INCLUDE:

- Smooth, repeatable motion and rigid design provide steady images in windy environments and excellent visual tracking
- Powerful command set supports absolute angle, relative angle, and velocity control with low latency and low jitter
- Extremely precise positioning (0.0075°) allows translating object positions to map coordinates accurately
- 3-axis strap-down gyro design
- Rigid worm gear design (no belts/pulleys)
- High holding torque (no sag when powered off)
- Solid and vibration-tolerant for vehicle-mounted applications
- Wide range of pan speeds (< 0.0075°/sec to 120°/sec)
- Integrated Ethernet and Web interfaces
- Increased command rates, reduced jitter
- Increased torque and speed
- Advanced microstep control



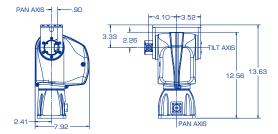
Specifications

Pan/Tilt Performance	Side Mount	Top Mount
Max. Payload ¹	20 lb (balanced)	12 lb
Pan Speed Range ²	0.0075°/sec – 120°/sec	0.0075°/sec – 120°/sec
Tilt Speed Range ²	0.0075°/sec – 120°/sec	0.0075°/sec – 120°/sec
Resolution – Pan	0.0075° (with microstep)	0.0075° (with microstep)
Resolution – Tilt	0.0075° (with microstep)	0.0075° (with microstep)
Pan/Tilt Features		
Tilt Range	+30° to -90° from level (120° range) (up to +/-90° with side mount if specified at time of order.)	
Pan Range	+/- 168° or 360° continuous	
Duty Cycle	Up to 100% duty cycle, or 3-5 million cycles	
Acceleration/Deceleration	On-the-fly spee	d and position changes
Power Requirements		
Input Voltage	Unregulated 12-30 VDC (fastest performance & torque @ 30 VDC)	
Input Protection	Over-voltage/over-current protection meets MIL-STD-1275D	
Power Consumption (Measured at 30 VDC)	33.0W (Low move power mode), 45.0W (Regular move power mode) 63.0W (High move power mode), 3.3W (Hold power off mode)	
Connections & Communi	cations	
Base Connectors	PRIMARY: 32-pin (MIL-C-26482). Includes: PTU-Power (3c) - 12-30 VDC + shield PTU-Control (7C) RS-232 (3c) & RS-485/422 (4c) Ethernet (4c) pan/tilt configuration/control Payload Pass-Through (9-12c)	
Payload Signal Pass-Through	Power (2c): 30 VDC max. @ 3 A Video-1 (2c): NTSC/PAL/RS-170 Video-2 (2c): NTSC/PAL/RS-170 High-Speed Pass-Through (4c): capable of 10baseT Other (3c): 30 VDC max. @ 1 A Connector: 19-pin (MIL-C-26402) Computer Controls RS-232, RS-485/422, Ethernet	
Control Protocols	DP (ASCII, Binary), Pelco-D (option), Nexus-compatible	
Mechanical		
PTU Weight	19 lb	
PTU Dimensions	Pan/Tilt only: 12.56" (h) × 8.2" (w) × 7.9" (d)	
Payload Mounting	Single/dual-side mount, top mount	
PTU Mounting	Pedestal	
Material	Machined alum	inum, stainless fittings
Packaging & Environmer	ital	
Standards	IP67 Certified	
Operating Temperature ³	-30°C to 7	70°C (no heaters)
Humidity	100% relative hu	imidity, non-condensing
Ice (Operating)	Sustained operati	on with 0.25" ice buildup
Dust/Sand (Operating)	Sustained exposi	ure to blowing dust/sand
Wind/Rain/Fog	IP67	
Salt Spray	MIL-810G Salt Spray	
Color/Finish	Black anodized; custom colors/finishes available	
Shock/Vibration Certifications		6 Vibration, Method 516.6 Drop Test, d 516.6 Shock

¹Over-the-top payload assumes COG < 6" from tilt axis; over the side payload assumes balanced COG.

²Maximum speed may depend on exact payload inertia and input voltage.

³Reduced speeds may be required for low temperature operation.



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